



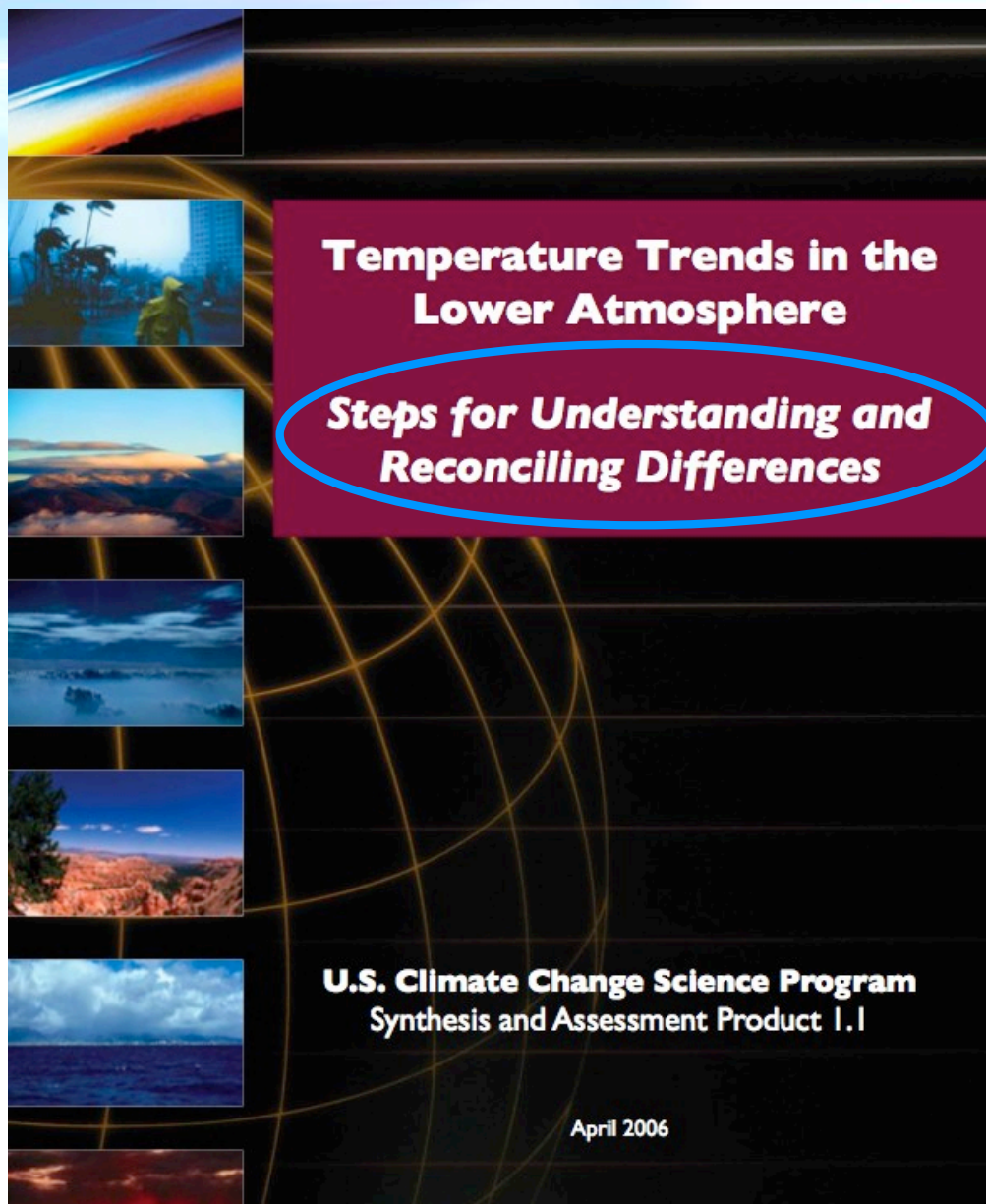
3-Way Comparison between AIRS, ECMWF and GPS Temperatures in Upper Troposphere and Stratosphere

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Brian Wilson and Gerald Manipon

Jet Propulsion Laboratory
California Institute of Technology

AIRS Science Meeting
Pasadena, CA

29 March 2007





Some Key Points

- Adjustments to data are generally subjective and can be large compared to the actual trend.
- Reported trends vary considerably between groups *using the same data* owing to differing adjustment methods.
- Most *models* predict greater warming in the troposphere; most *observations* show greater warming at the surface. *The likely cause is errors in the tropospheric observations.*
- Recent adjustments have brought satellite observations into closer agreement with models.
- “Satellite observations tend to be bias-corrected to the model.”
(*Healy & Thépault*, 2006) [ECMWF]



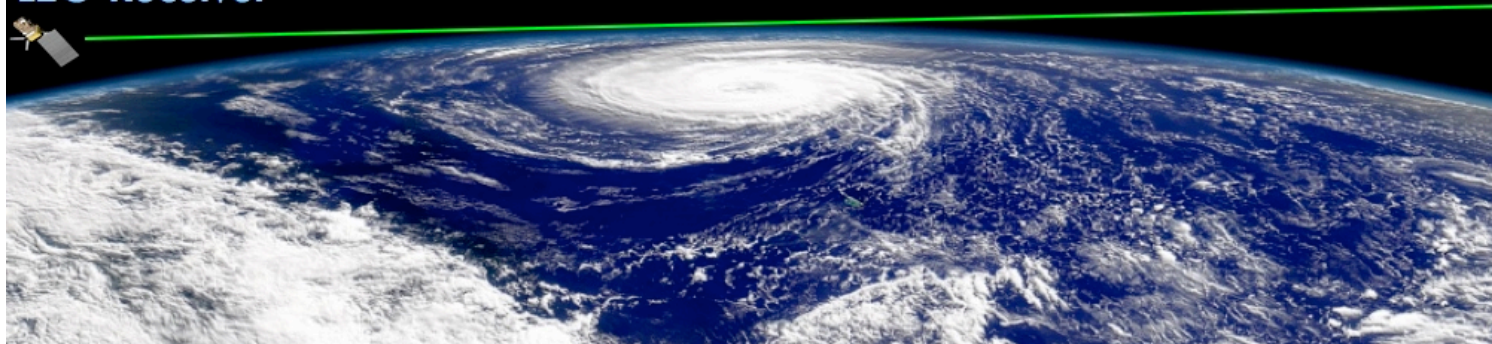
One Approach

GPS Atmospheric Occultation

- High resolution profiles of:
 - Bending angle
 - Refractivity
 - Density
 - Pressure
 - **Temperature** / Moisture
 - Geopotential heights
- Temporal and spatial averages, 2D maps
- Global pressure contours, gradients, and geostrophic wind fields

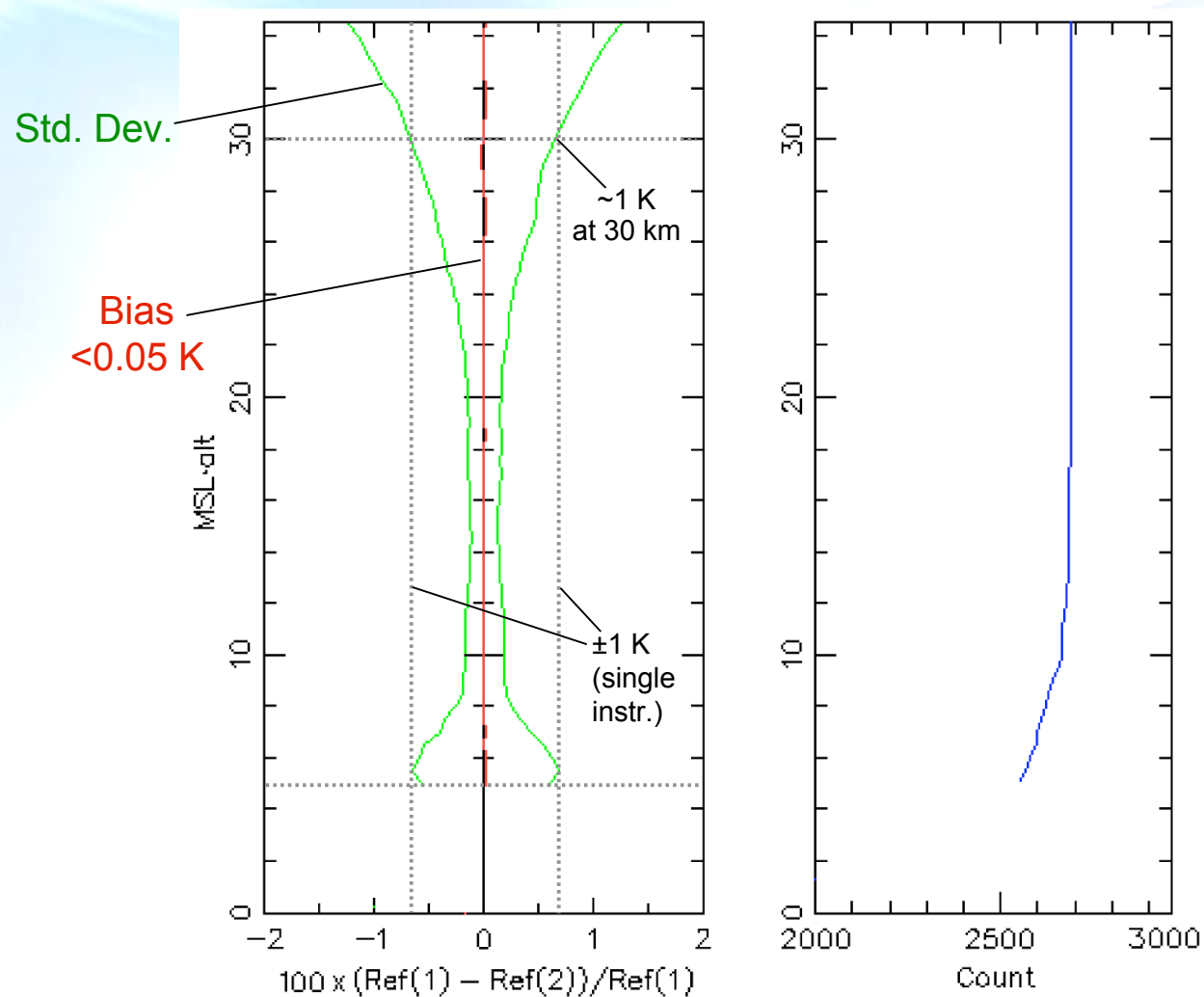
LEO Receiver

To GPS →





GPS-GPS Comparison Stats from COSMIC



No cloud or
weather
sensitivity

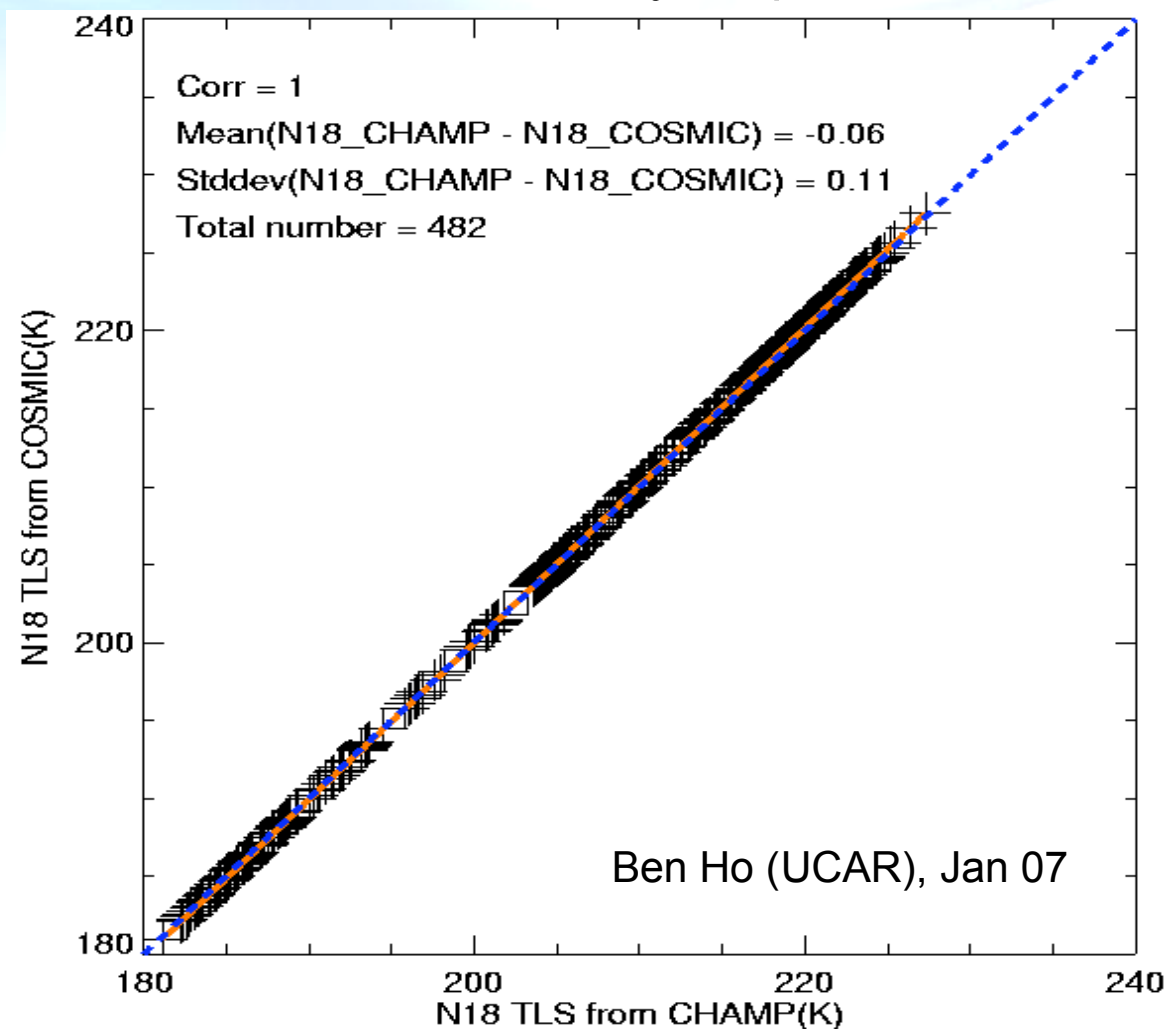
No corrections
or calibrations
required

Performance
traceable to an
absolute SI
standard

Ben Ho (UCAR), Jan 07



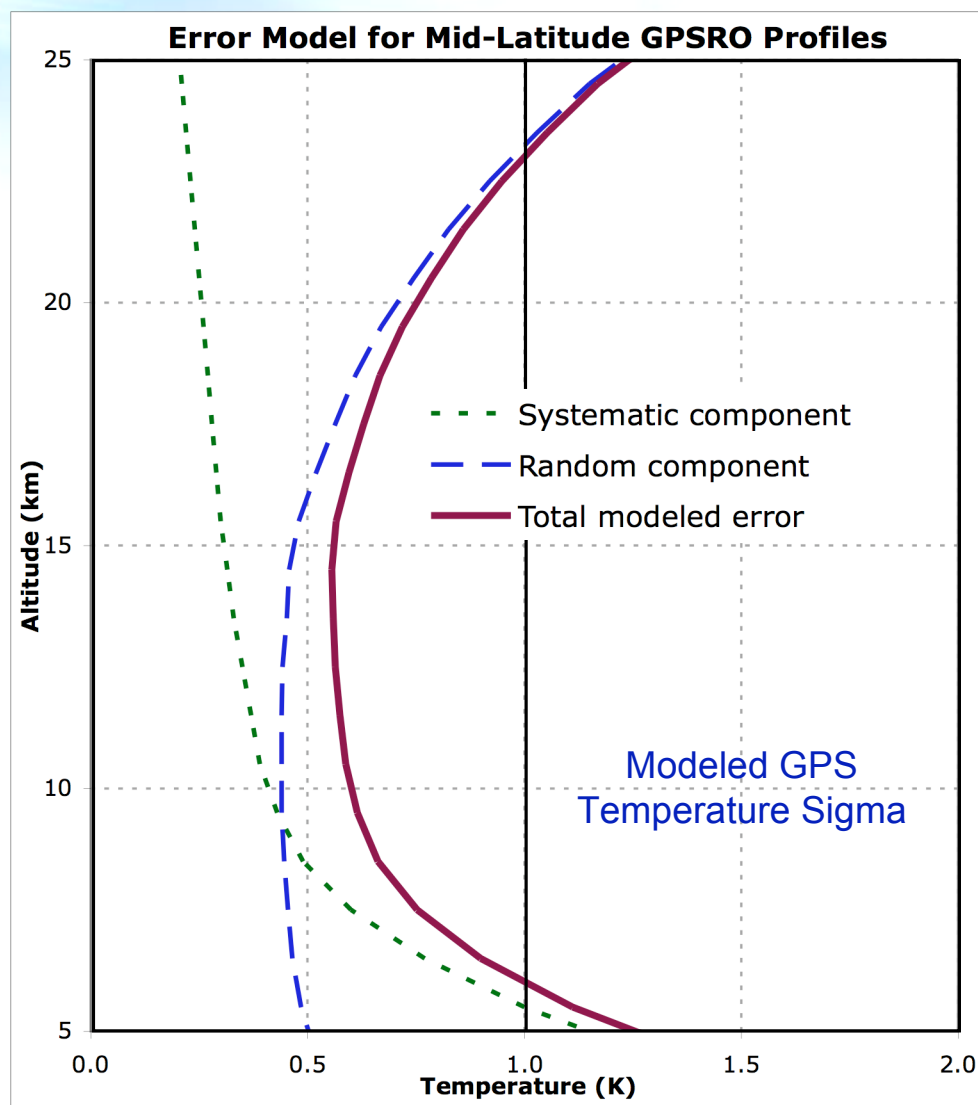
TLS Comparison with GPS Sensors Launched 6 yrs Apart



N18 TLS est. from COSMIC v. N18 AMSU TLS est. from CHAMP



Modeled GPSRO Temperature Sigma

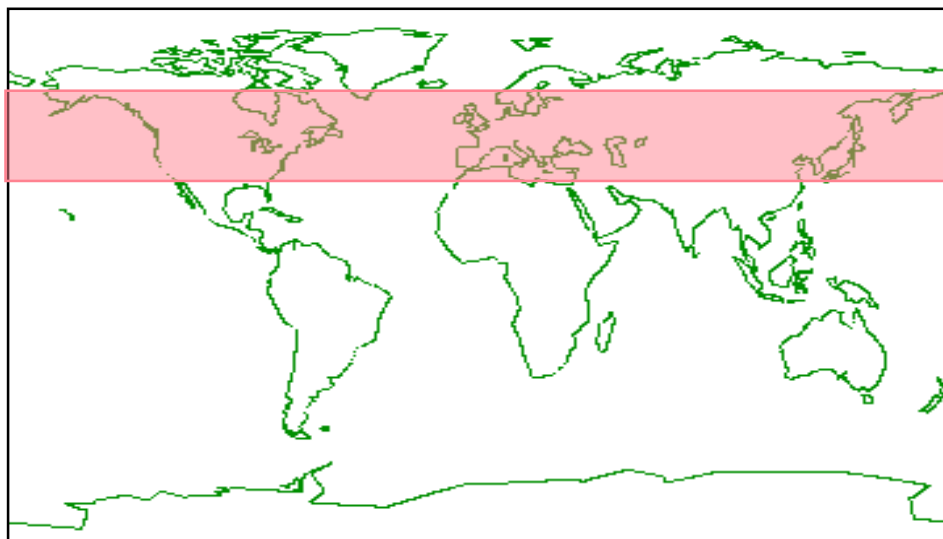




Controlled Three-Way Comparison:

- AIRS-ECMWF-GPS temperatures
- Common set of 3-way match-ups
- For all of 2003 (Champ, SAC-C)

ECMWF
“Sweet Spot”

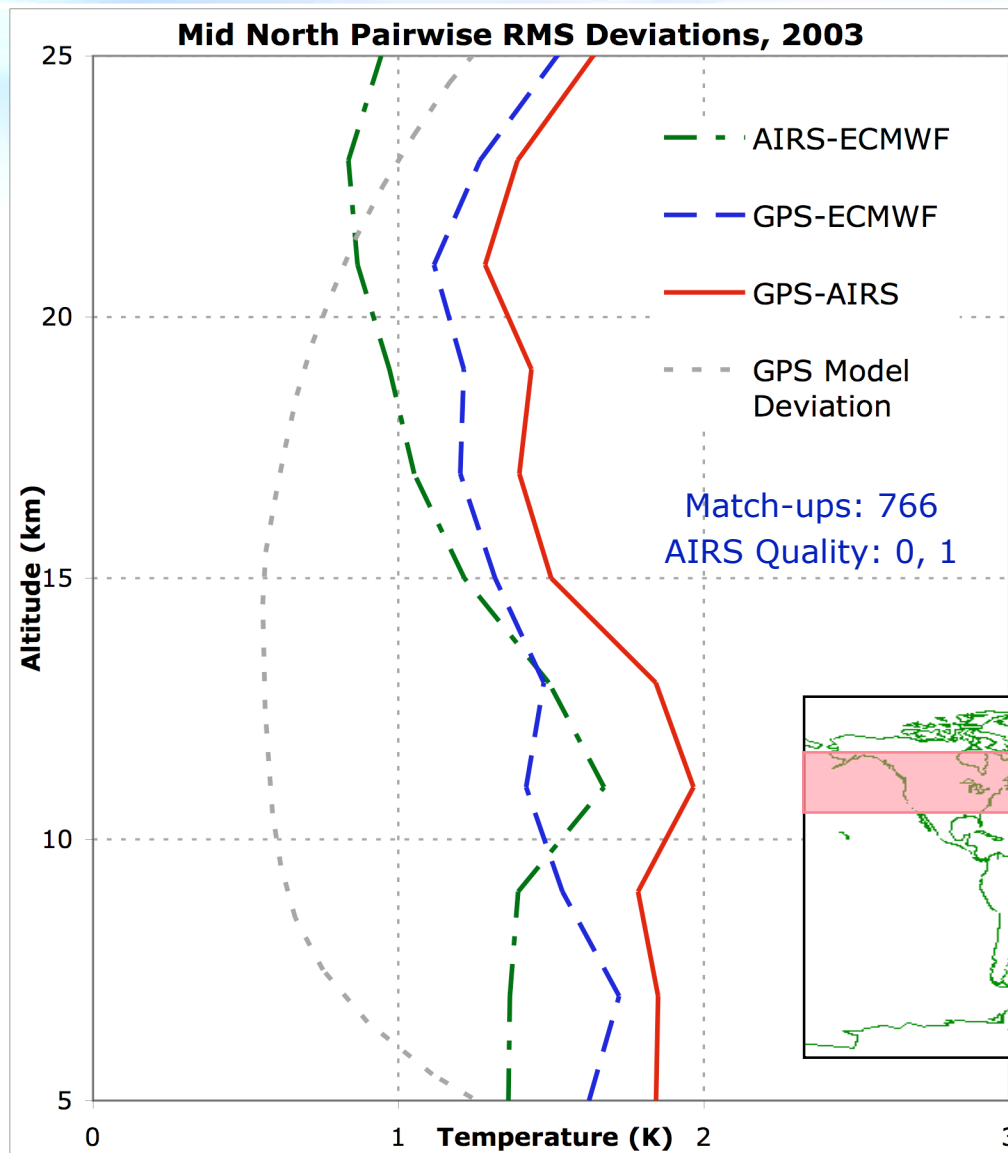


First comparisons:
30°-60° North
("Mid North")

Match-up criteria: <200 km, <2 hrs apart



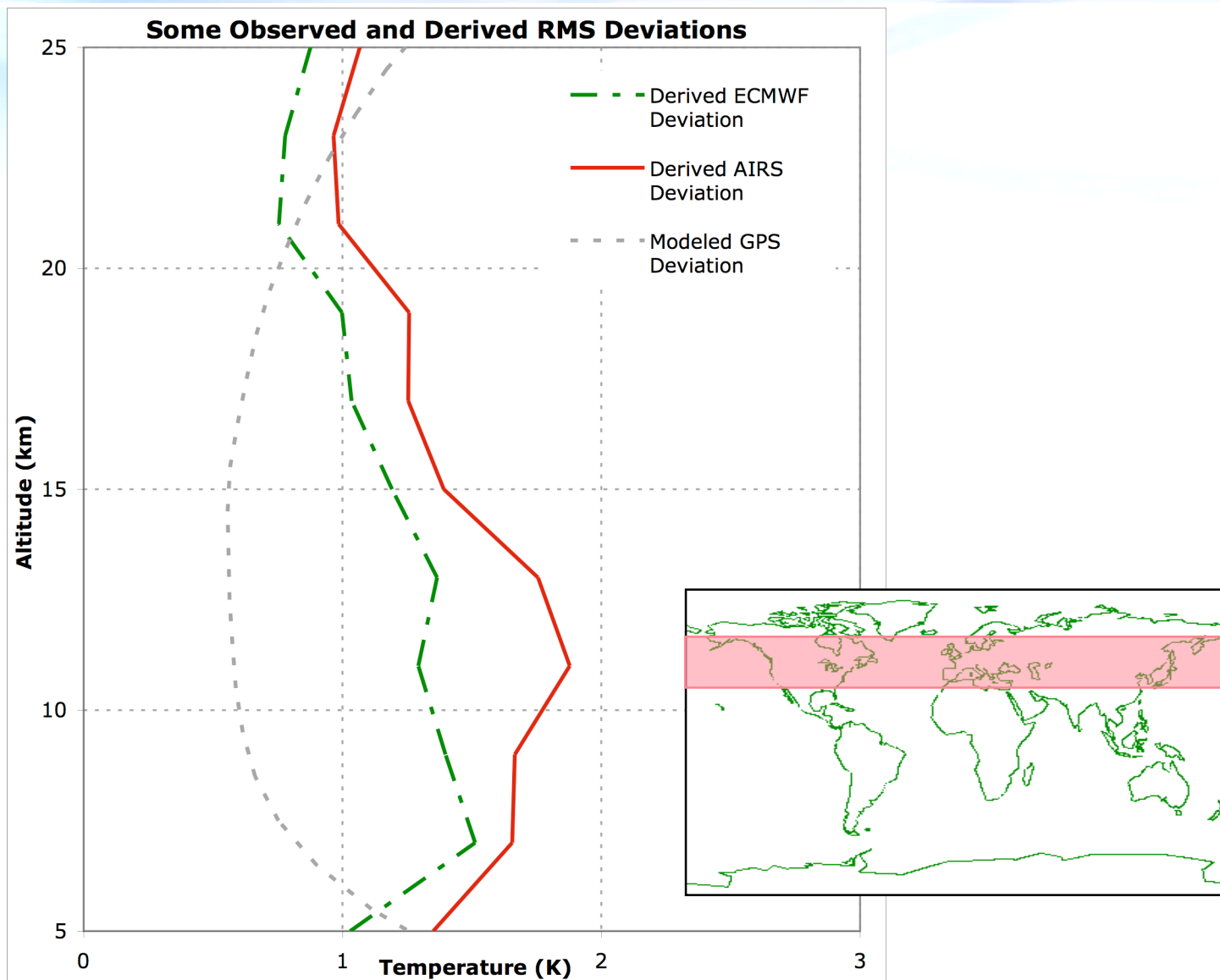
Pairwise RMS deviations



A Puzzle

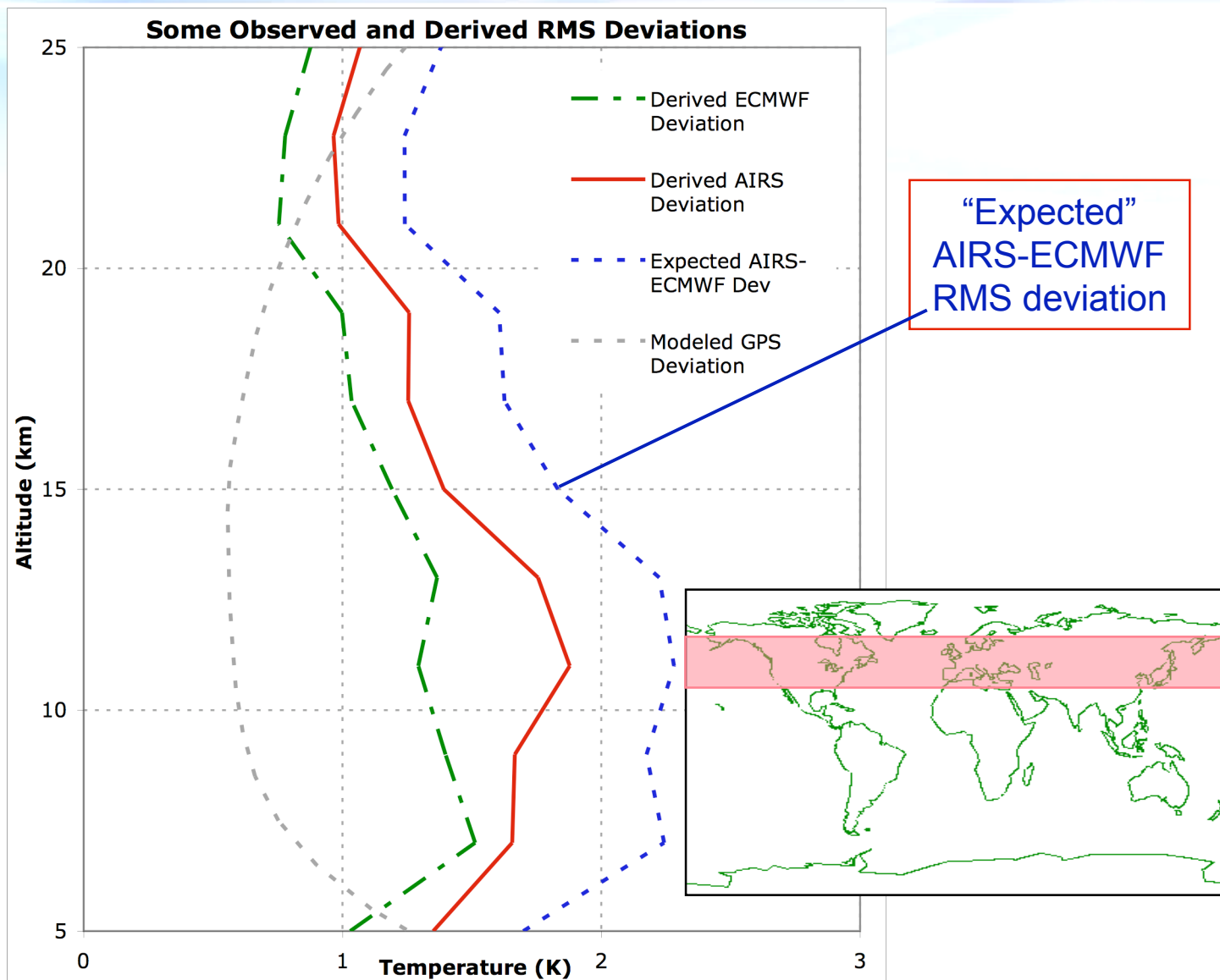


Derived AIRS & ECMWF RMS deviations



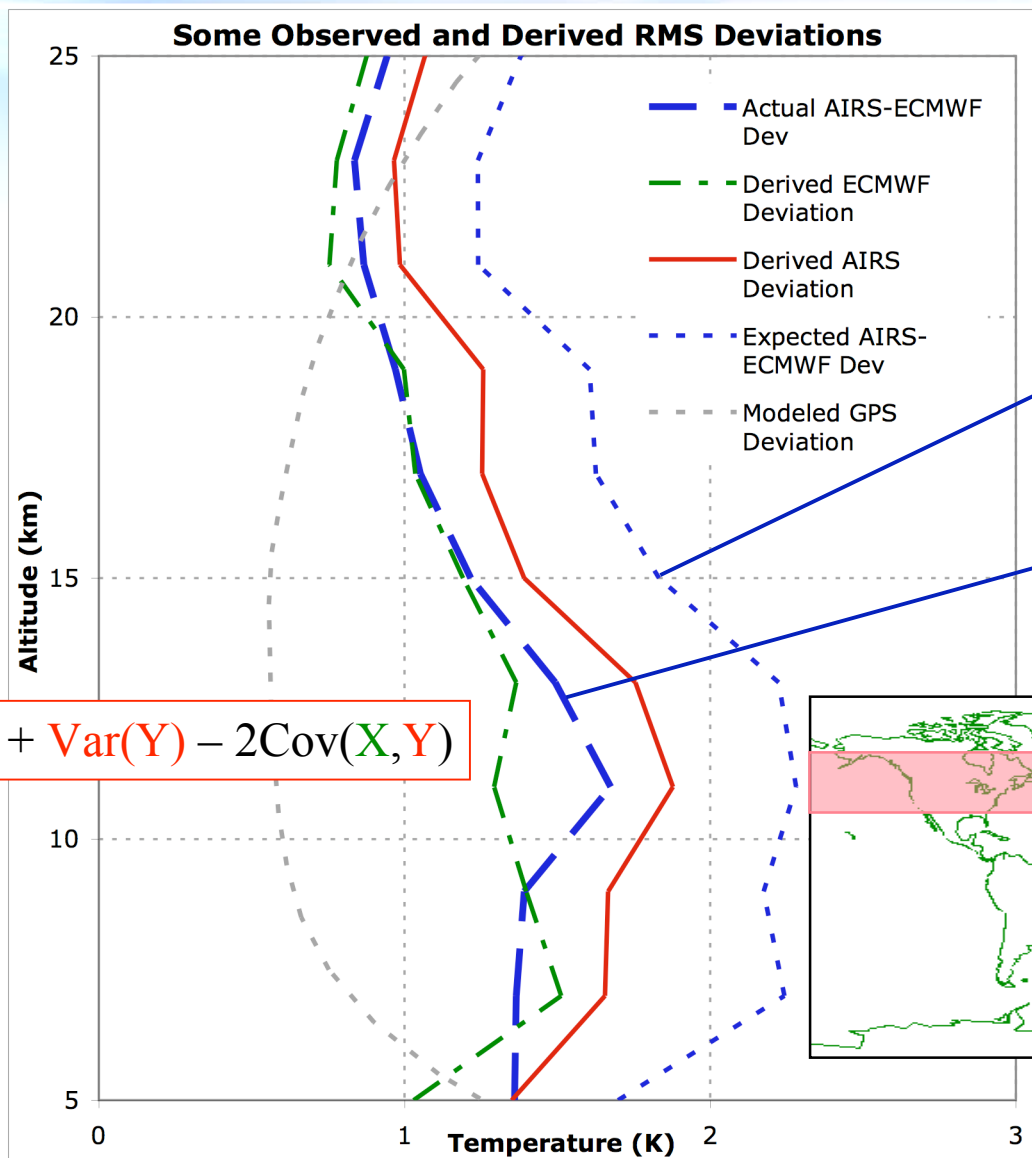


Derived AIRS & ECMWF RMS deviations





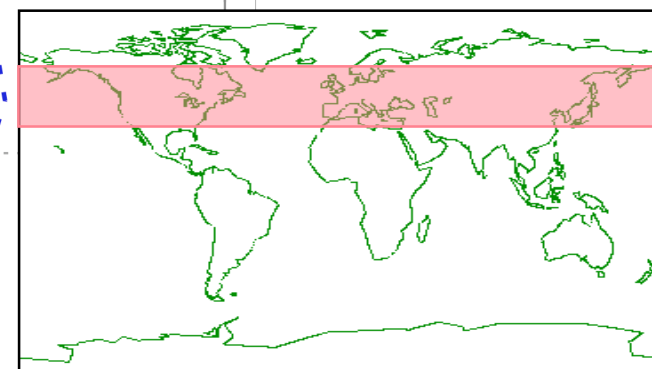
Derived AIRS & ECMWF RMS deviations



“Expected”
AIRS-ECMWF
RMS deviation

Actual
AIRS-ECMWF
RMS deviation

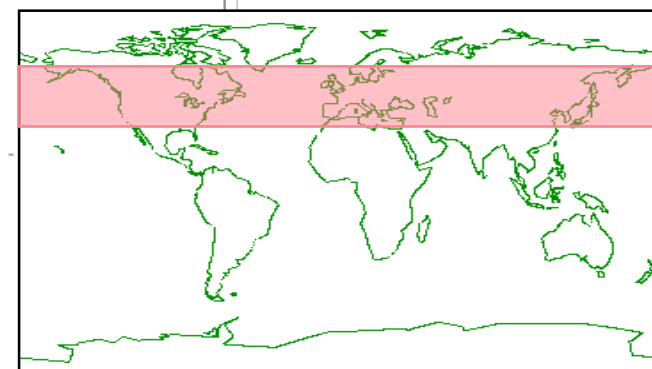
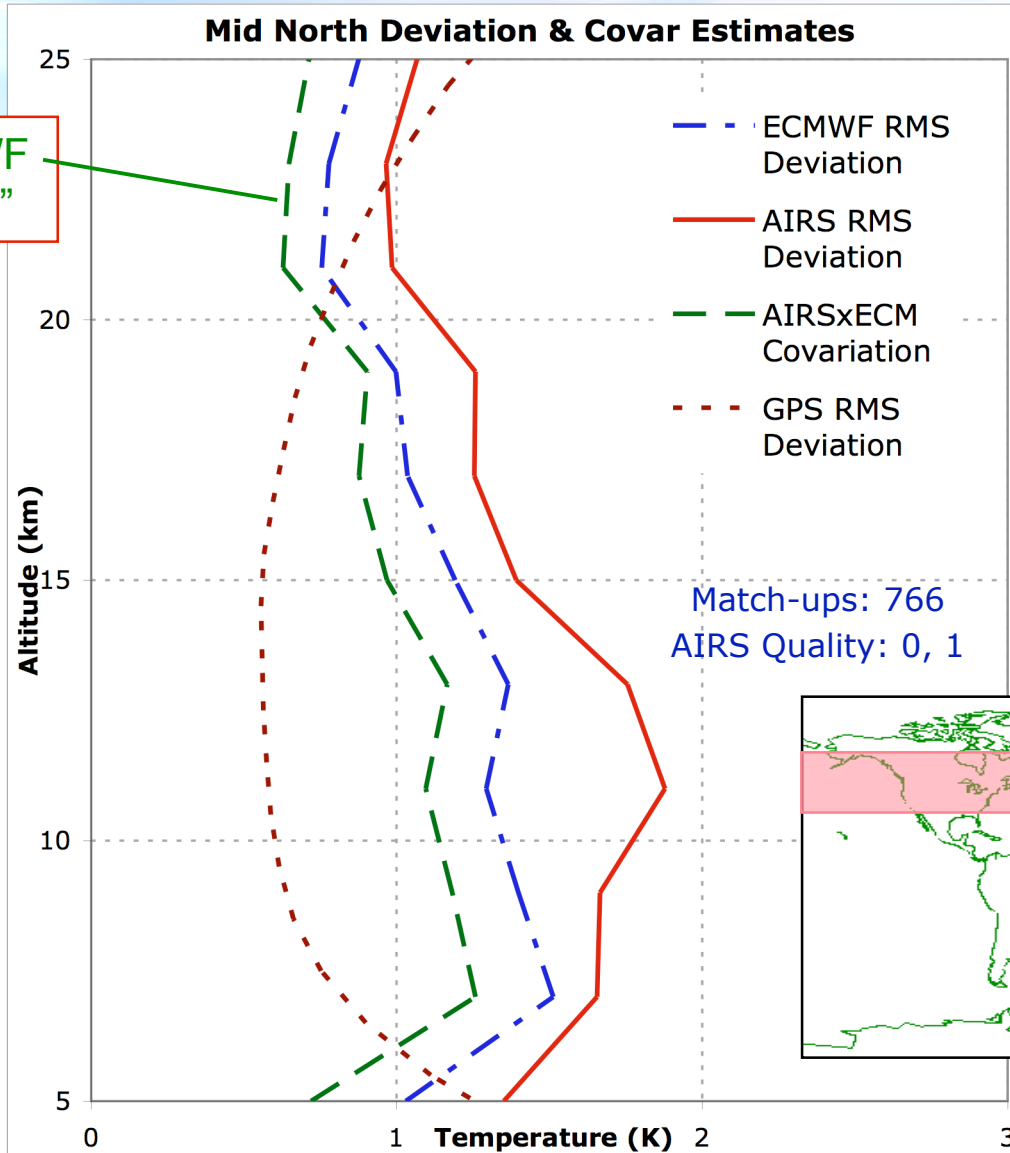
$$\text{Var}(X-Y) = \text{Var}(X) + \text{Var}(Y) - 2\text{Cov}(X,Y)$$





Derived AIRS & ECMWF RMS deviations

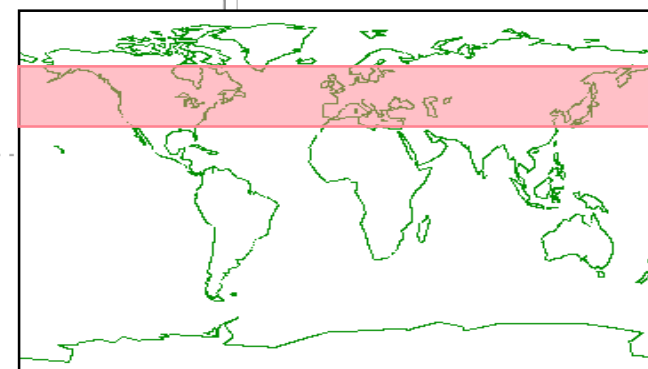
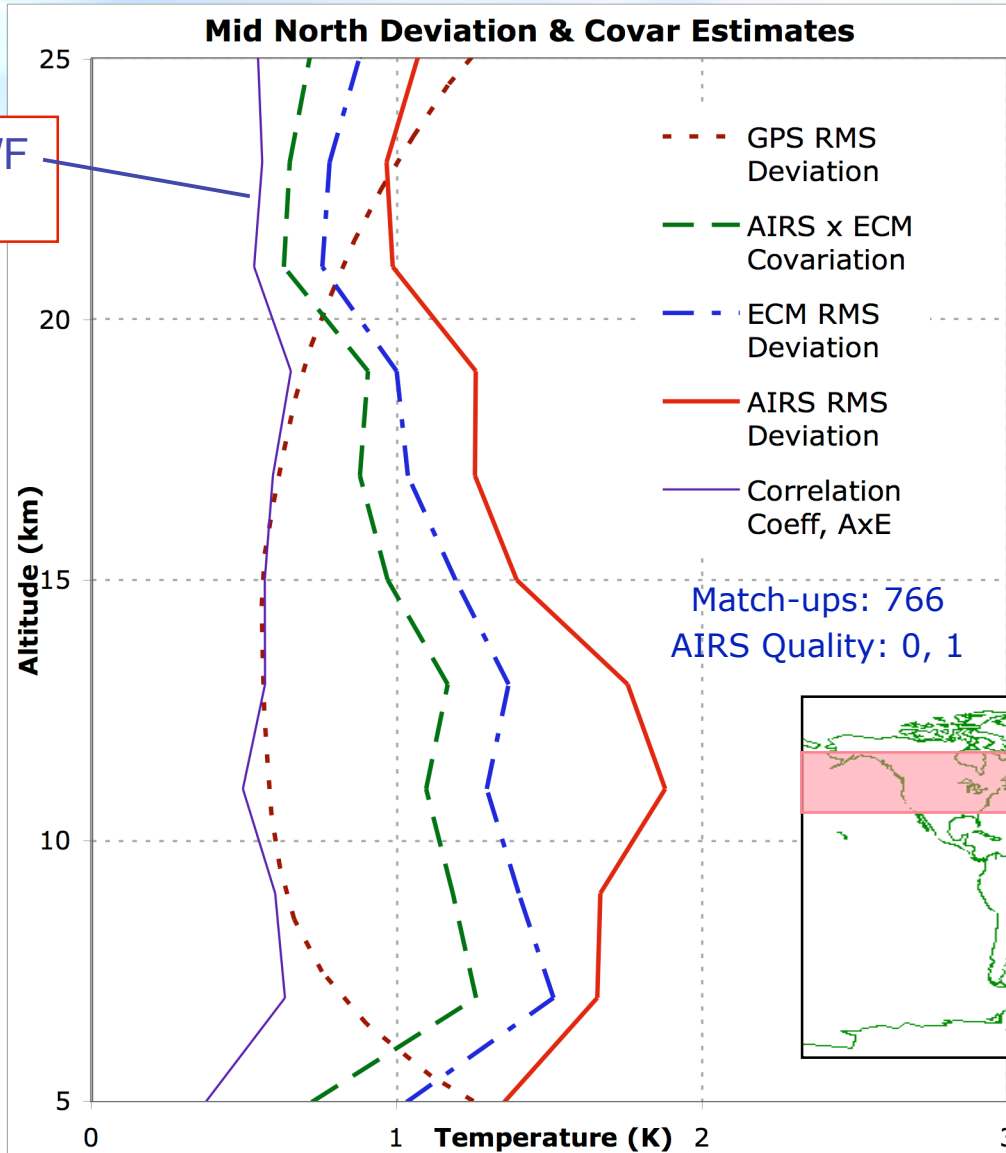
AIRS-ECMWF
"Covariation"





Derived AIRS & ECMWF RMS deviations

AIRS-ECMWF
Corr. Coeff.

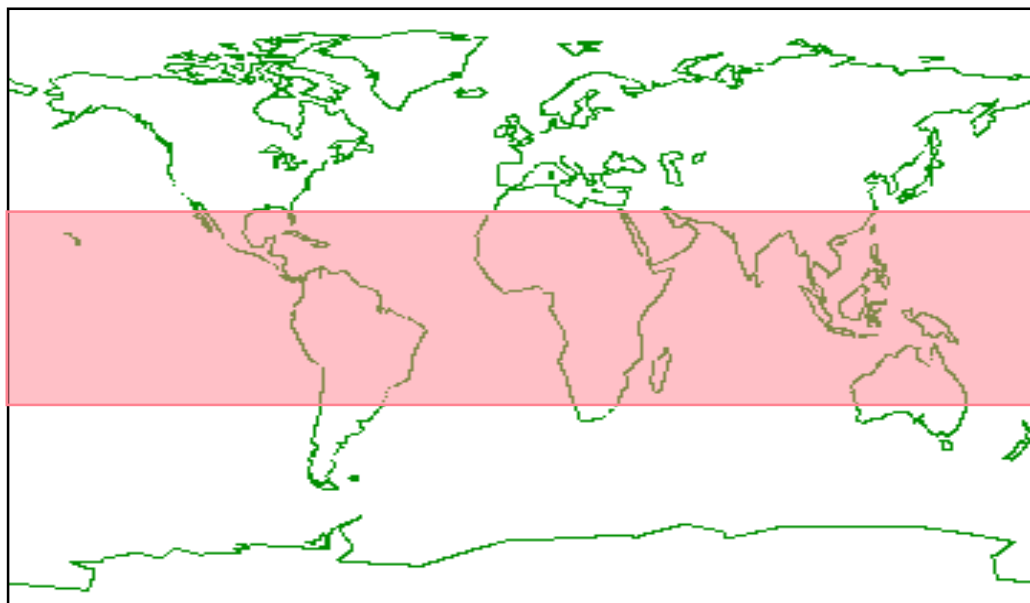




How else can we examine this question?

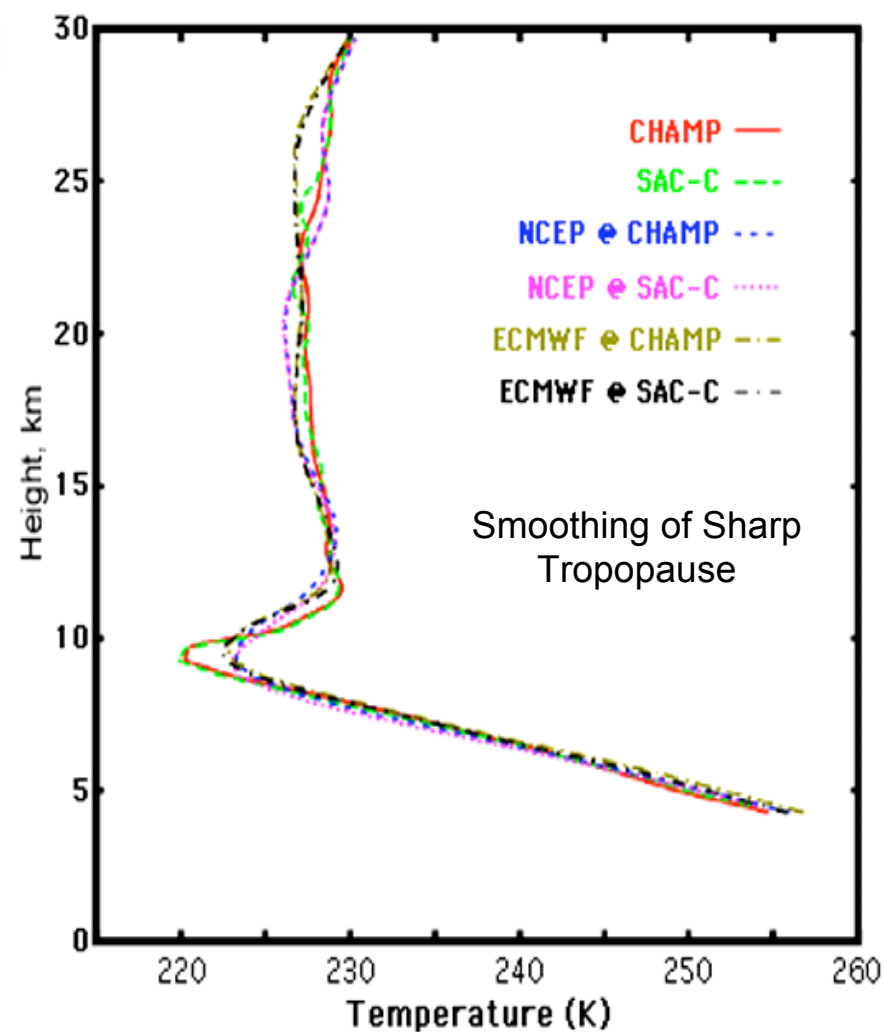
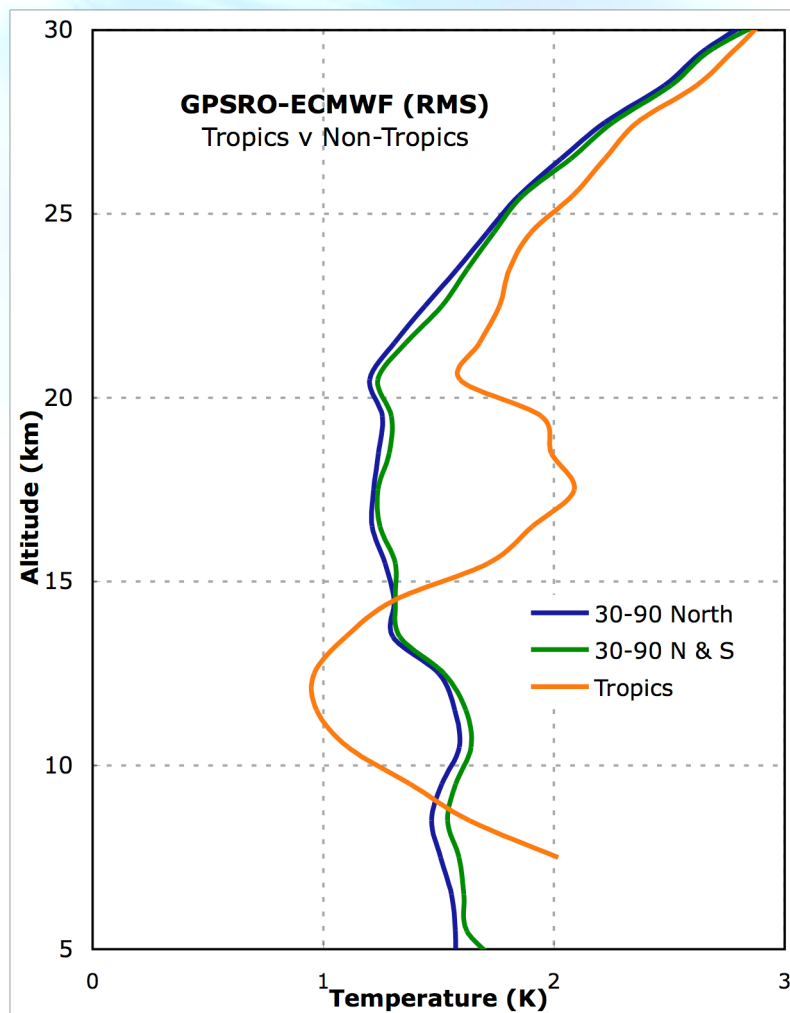
Compare regional performance variations, where
a particular technique is known to vary in a
particular way

I – The Tropics



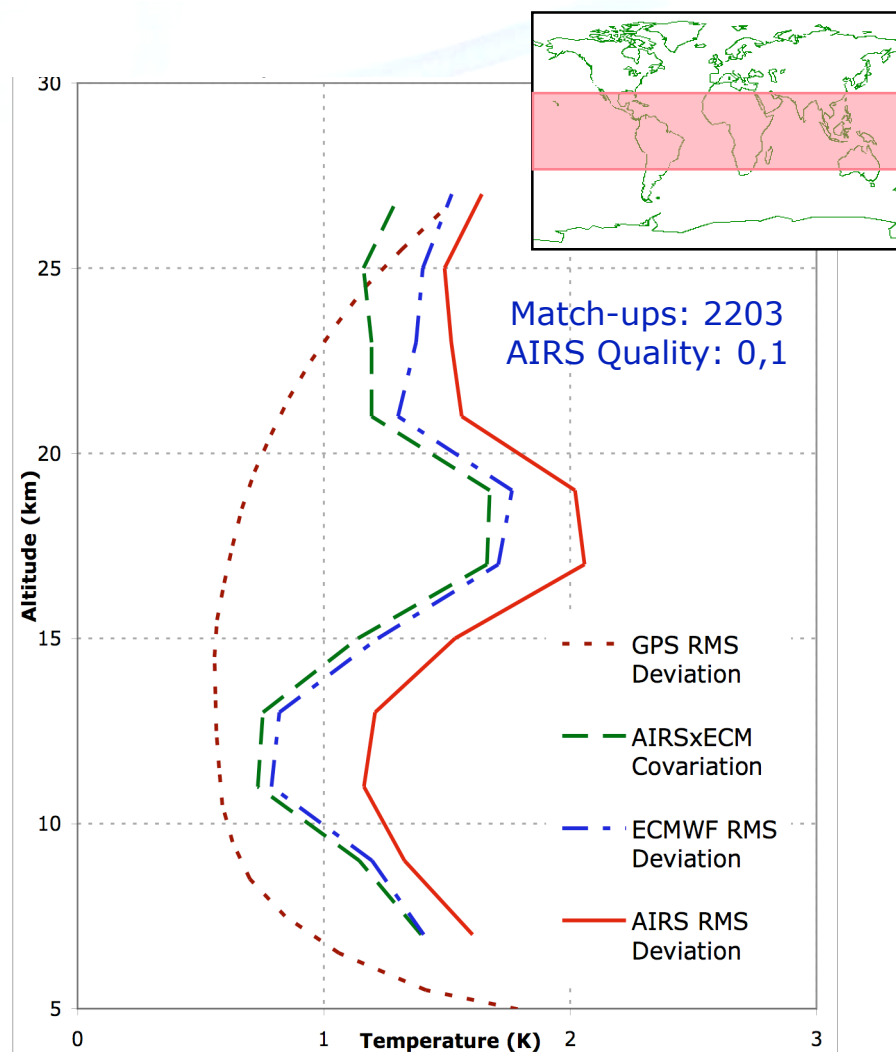
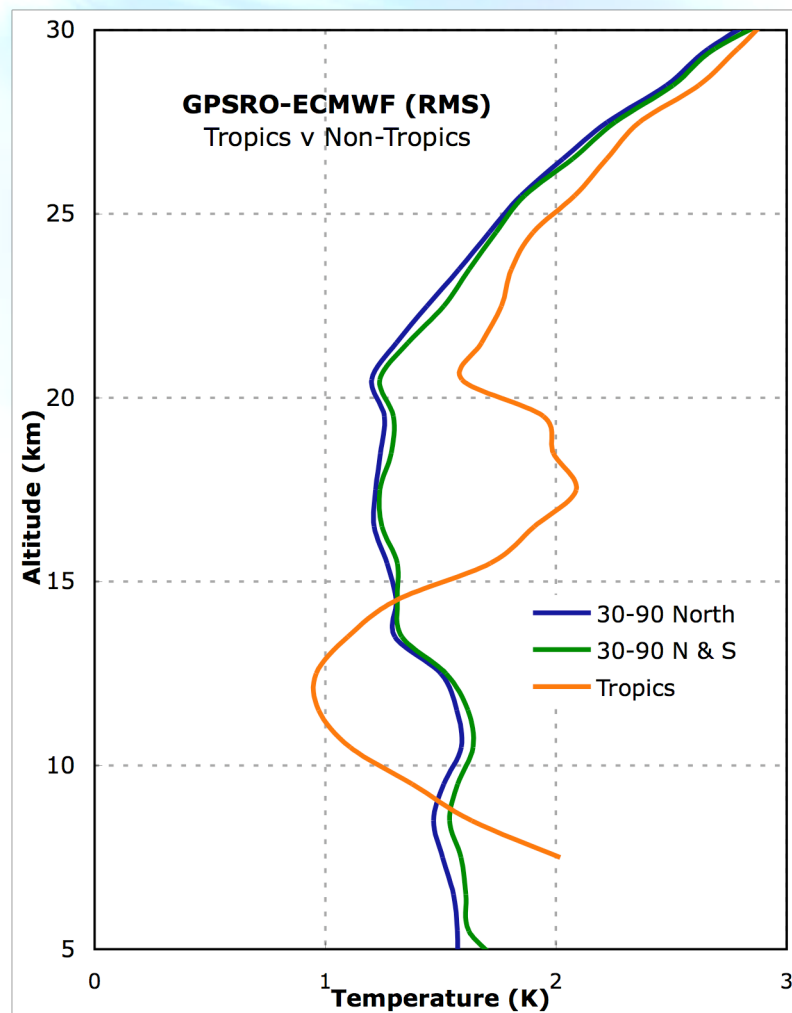


ECMWF-GPS RMS Deviations, 2003





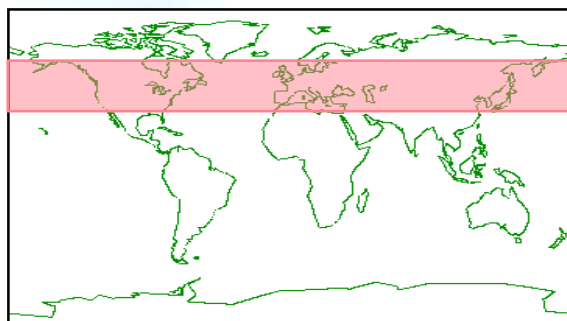
ECMWF-GPS RMS Deviations and Means, 2003



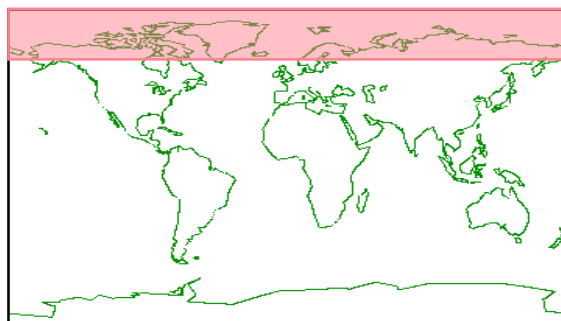


Regional Performance Variations – II

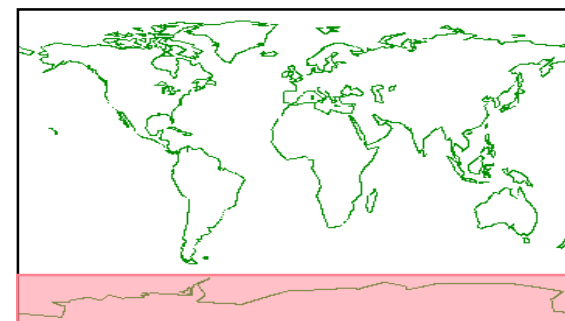
Vertical Bias Patterns



Mid North



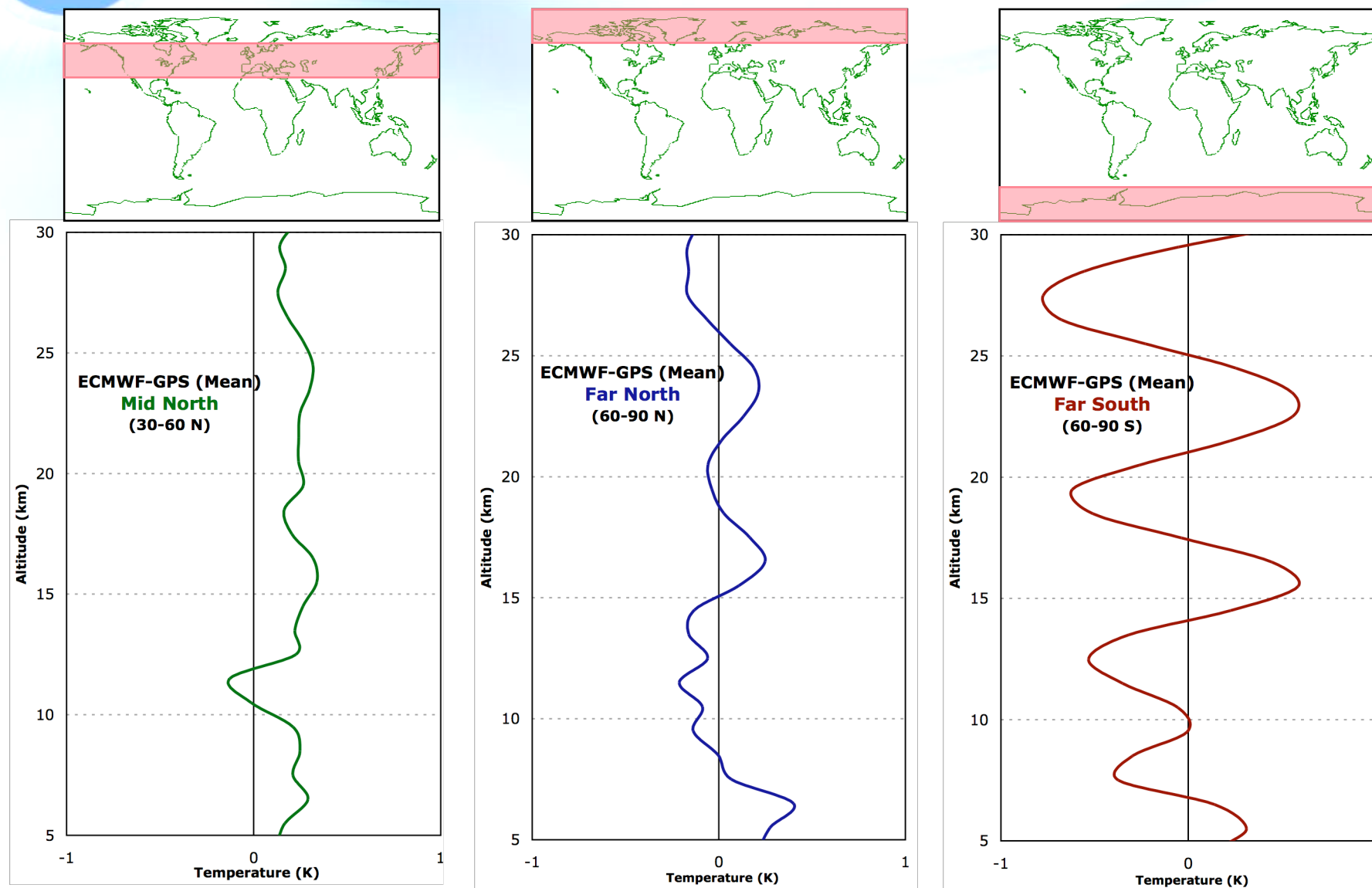
Far North



Far South

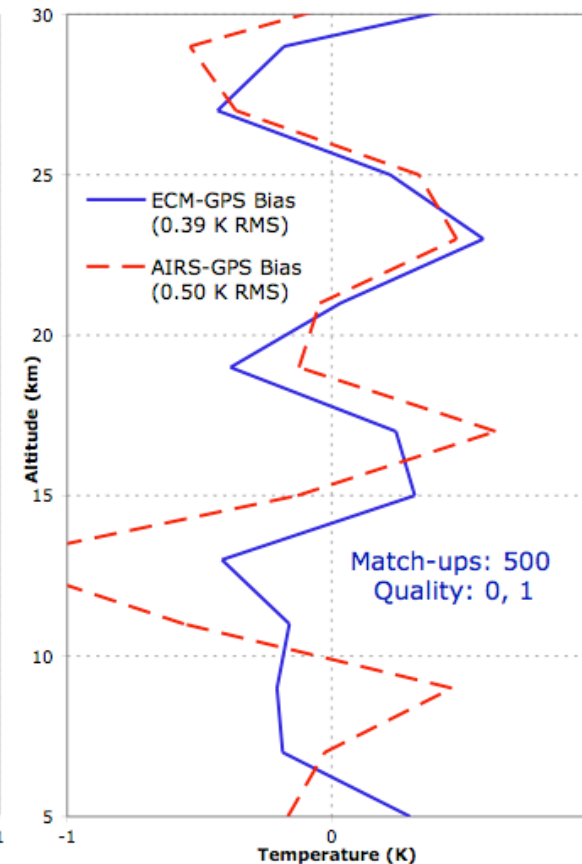
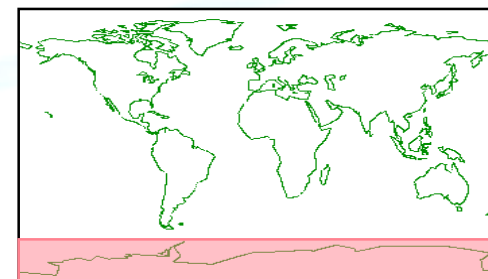
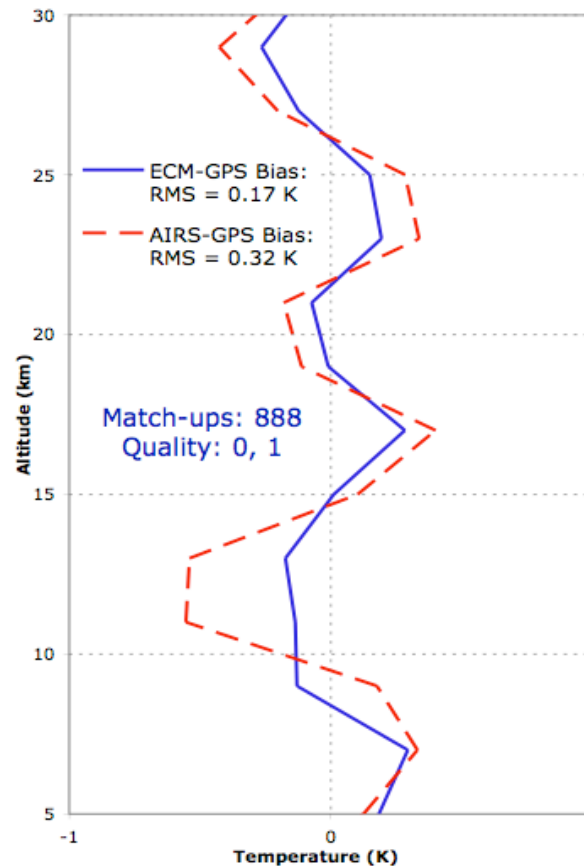
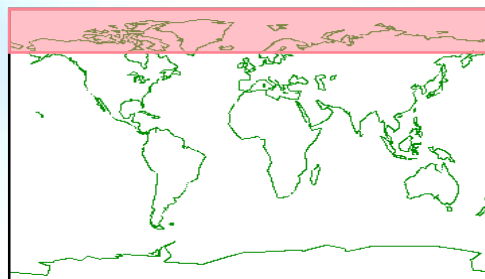
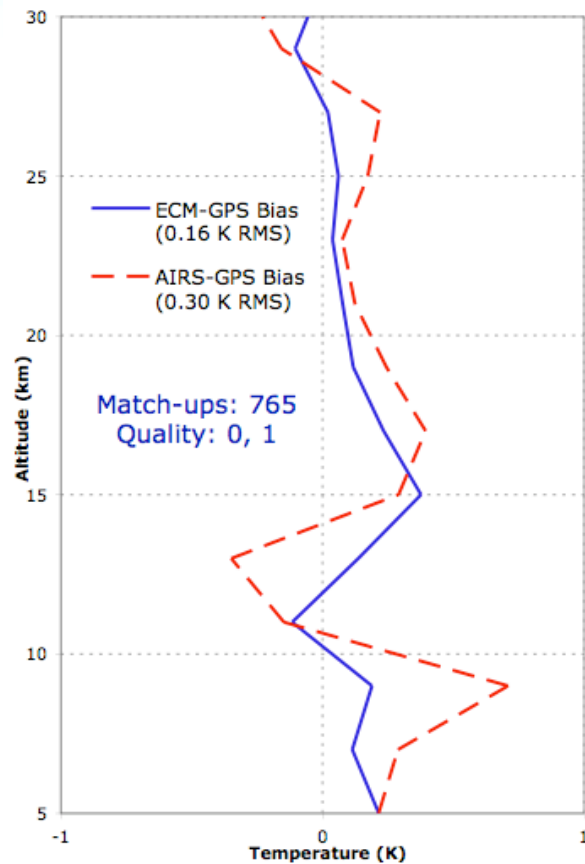
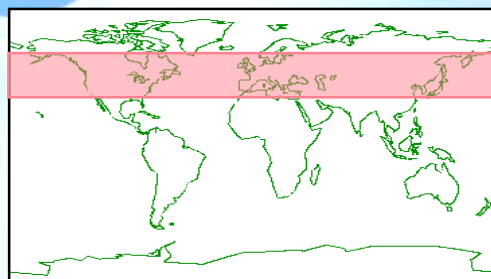


ECMWF-GPS Means, All GPS, 2003





ECMWF & AIRS Means vs GPS, All 2003





Conclusion

IF our GPSRO error model is accurate, then:

3-way comparisons show significant correlation between AIRS and ECMWF temperature errors.

Caveat:

We should adopt actual AIRS smoothing functions to ensure we are comparing like quantities.

Next:

Repeat the analysis with AIRS V5 and COSMIC data and true AIRS smoothing functions.



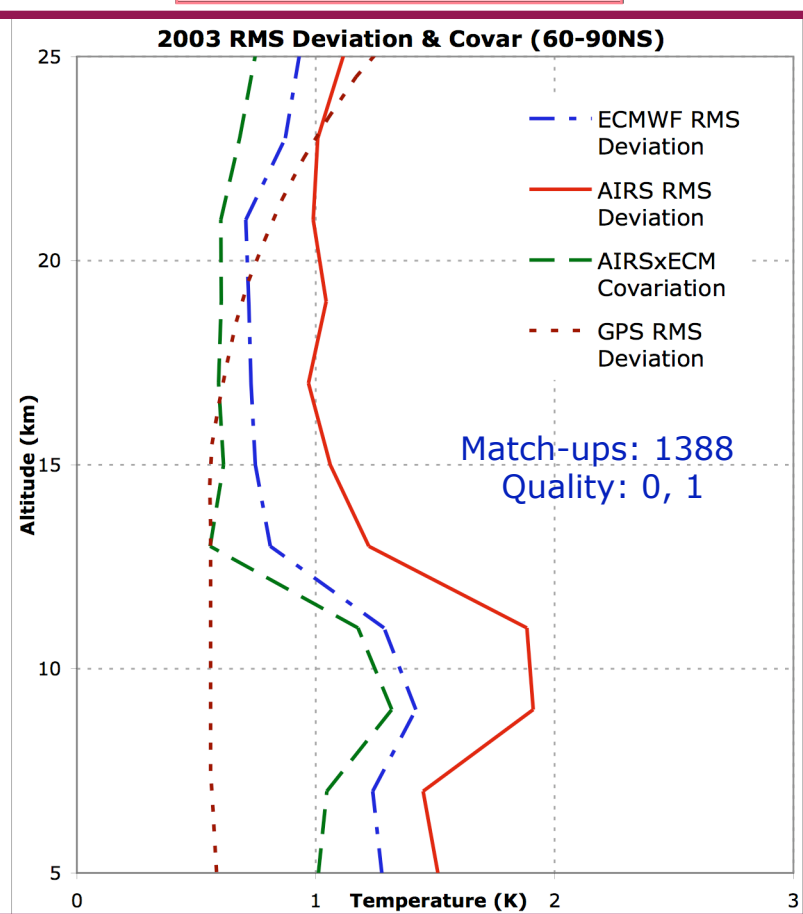
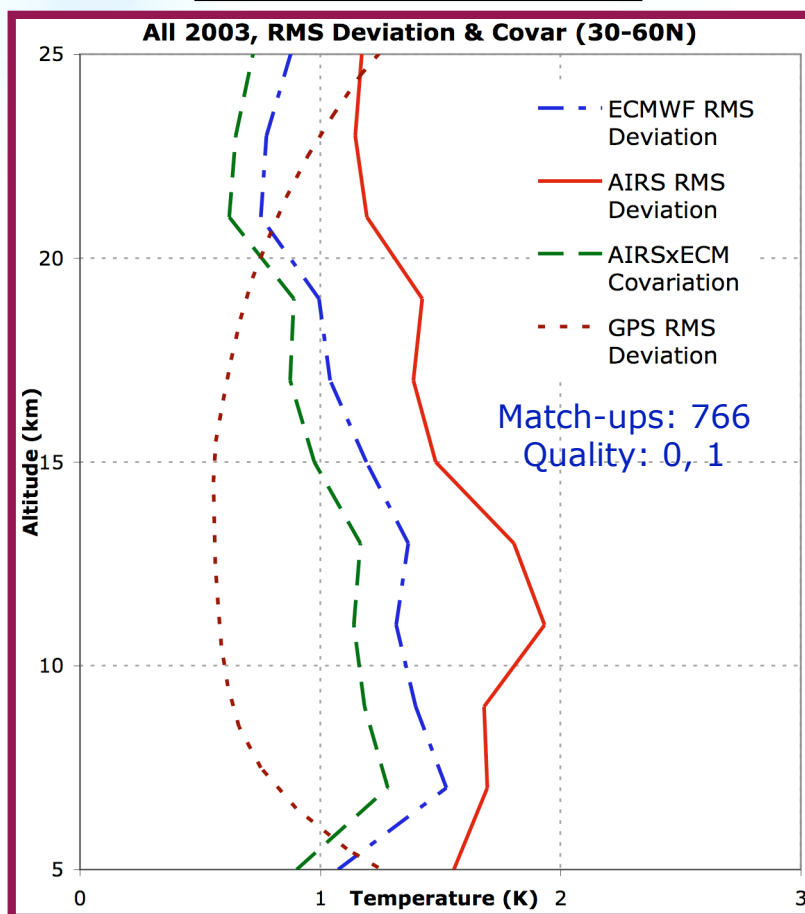
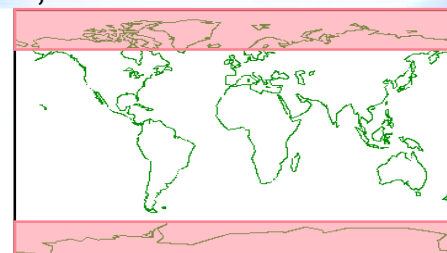
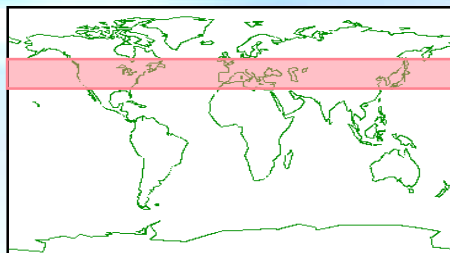
Backups



Comparison of AIRS-ECMWF-GPS Temperature Profiles



RMS Deviations & Covariation, All 2003

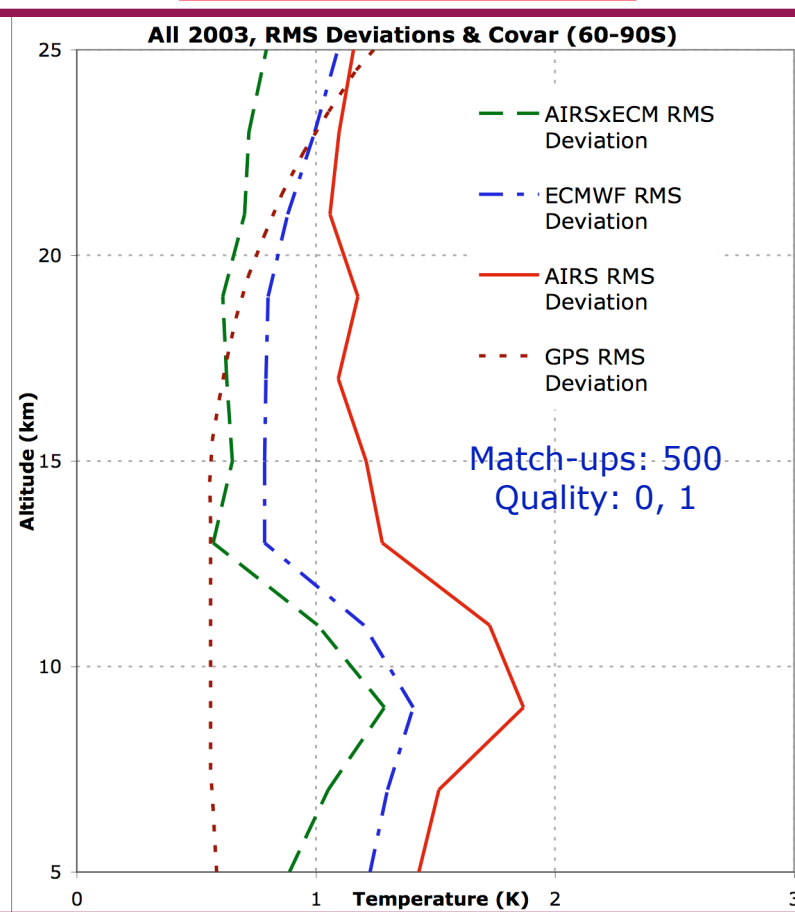
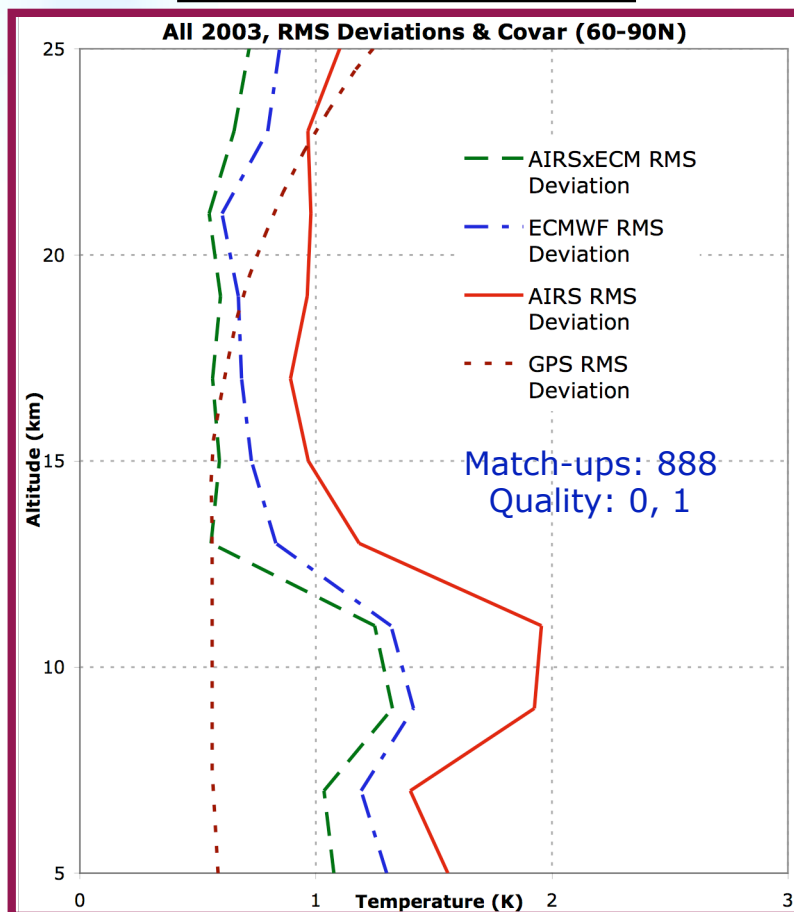
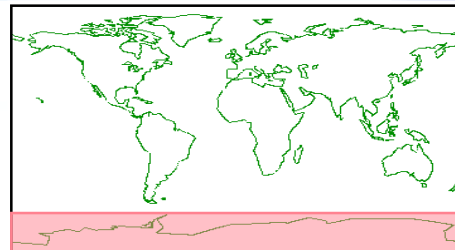
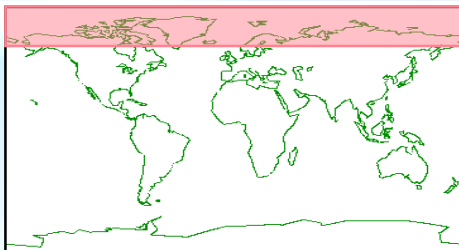




Comparison of AIRS-ECMWF-GPS Temperature Profiles



RMS Deviations & Covariation, All 2003



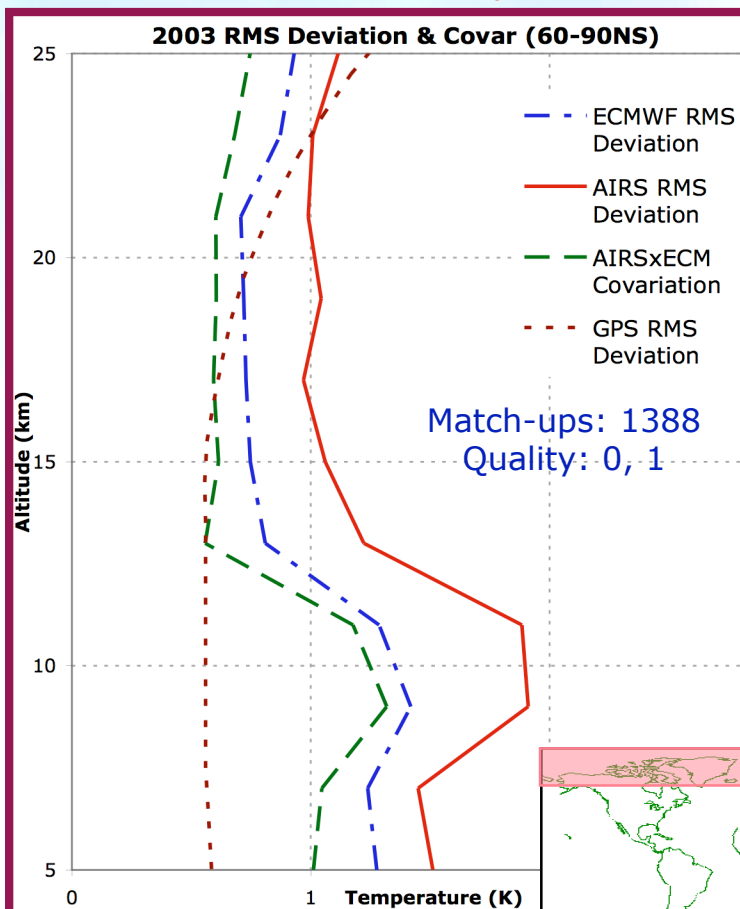


Comparison of AIRS-ECMWF-GPS Temperature Profiles

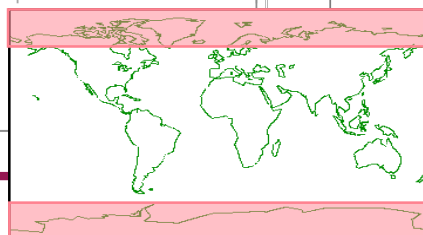
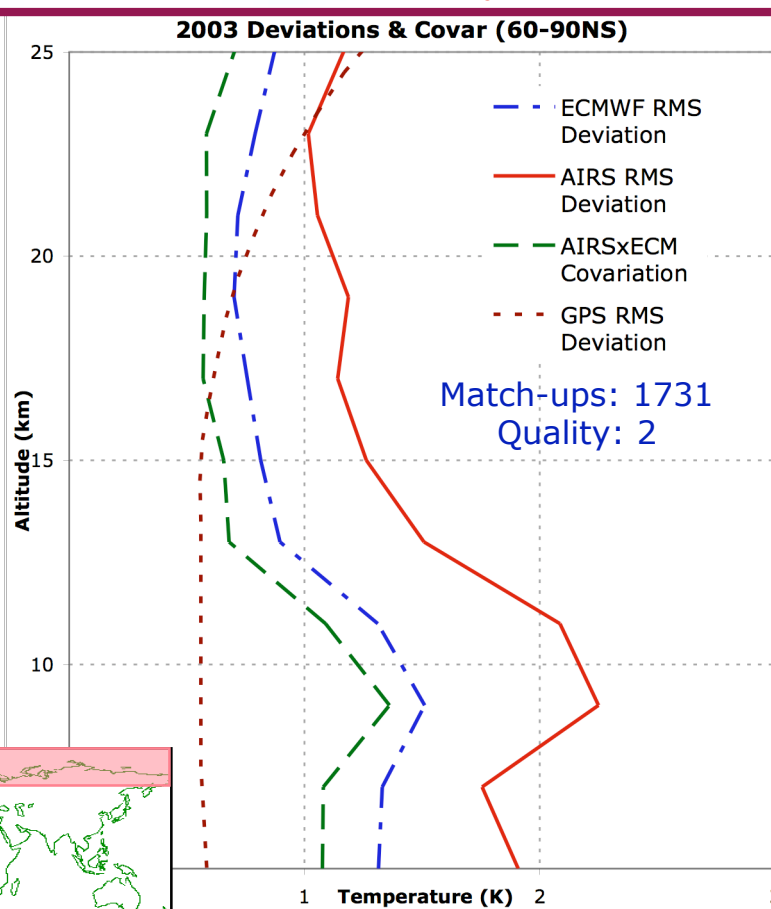


RMS Deviations & Covariation, All 2003

AIRS Quality 0,1



AIRS Quality 2





Simple Analysis

Measurement error = bias (b) + zero mean random error (e):

$$M_e = b + e$$

Measurement difference $M_1 - M_2$ is therefore:

$$\begin{aligned} M_{1,2} &= b_1 - b_2 + e_1 - e_2 \\ &= b_{1,2} + e_1 - e_2 \end{aligned}$$

The mean (expected) squared (MS) difference is therefore:

$$MS_{1,2} = b_{1,2}^2 + \sigma_1^2 + \sigma_2^2$$

(assuming e_1 and e_2 uncorrelated)



Or:

$$MS_{1,2} - b_{1,2}^2 = \sigma_1^2 + \sigma_2^2$$

(i.e., Var = MS - square of the mean)

For the three-way comparison we have:

$$(1) \quad MS_{1,2} - b_{1,2}^2 = \sigma_1^2 + \sigma_2^2$$

$$(2) \quad MS_{2,3} - b_{2,3}^2 = \sigma_2^2 + \sigma_3^2$$

$$(3) \quad MS_{1,3} - b_{1,3}^2 = \sigma_1^2 + \sigma_3^2$$



What this means:

Measurement difference $M_1 - M_2$ is:

$$M_{1,2} = b_{1,2} + e_1 - e_2$$

The mean squared (MS) difference is:

$$MS_{1,2} = b_{1,2}^2 + \sigma_1^2 + \sigma_2^2 - 2E[e_1 e_2]$$

~~(assuming e_1 and e_2 uncorrelated)~~



Revised Analysis

For the three-way comparison we now have:

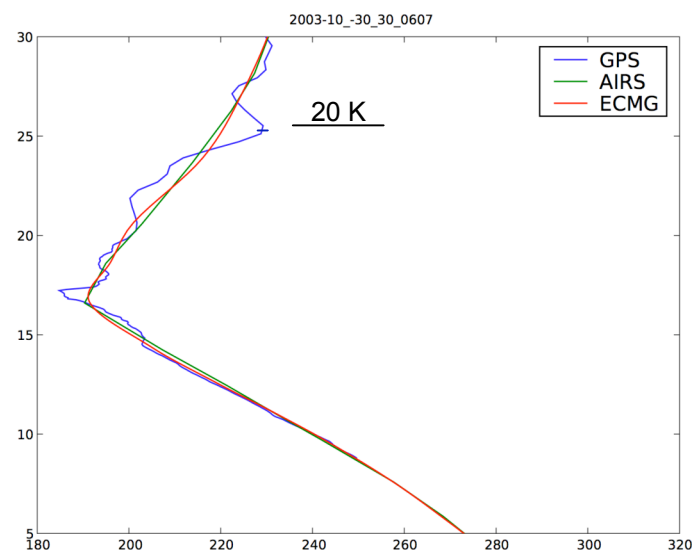
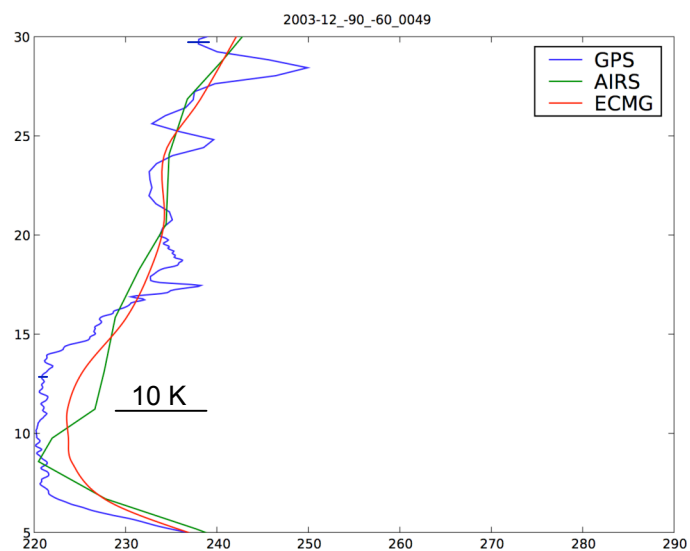
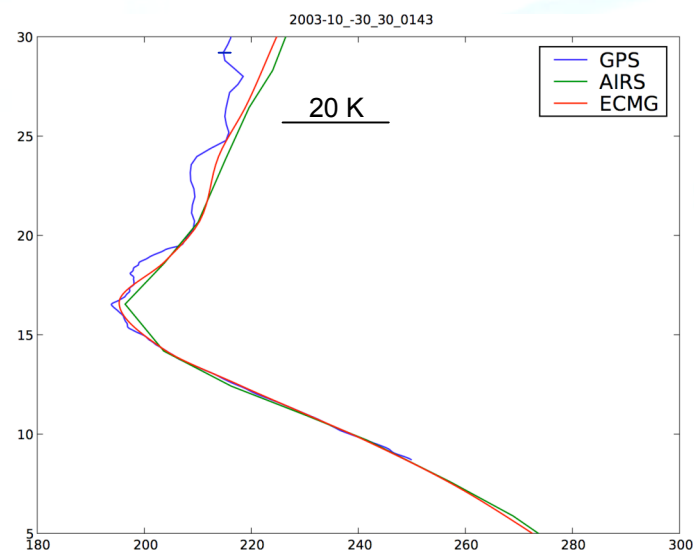
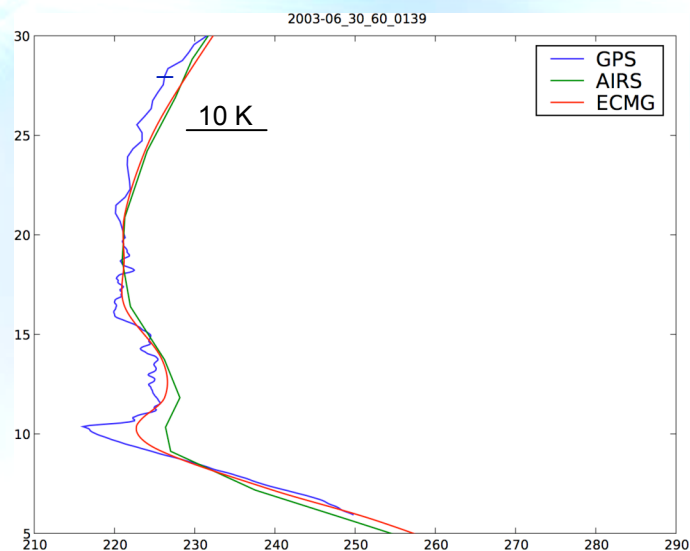
$$(1) \quad MS_{E,A} - b_{E,A}^2 = \sigma_E^2 + \sigma_A^2 - 2\gamma_{E,A}^2$$

$$(2) \quad MS_{A,G} - b_{A,G}^2 - \sigma_G^2 = \sigma_A^2$$

$$(3) \quad MS_{E,G} - b_{E,G}^2 - \sigma_G^2 = \sigma_E^2$$



Examples of AIRS-ECMWF Temperature Error Similarity



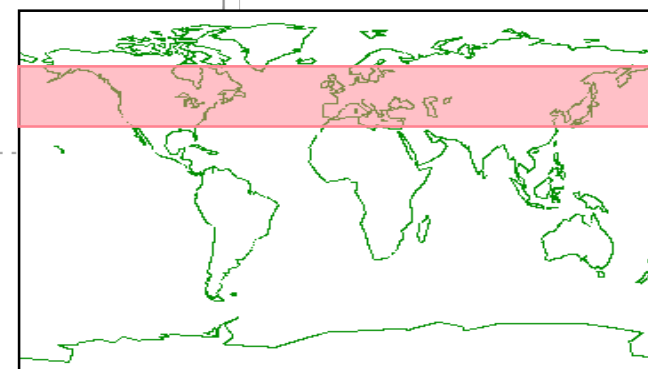
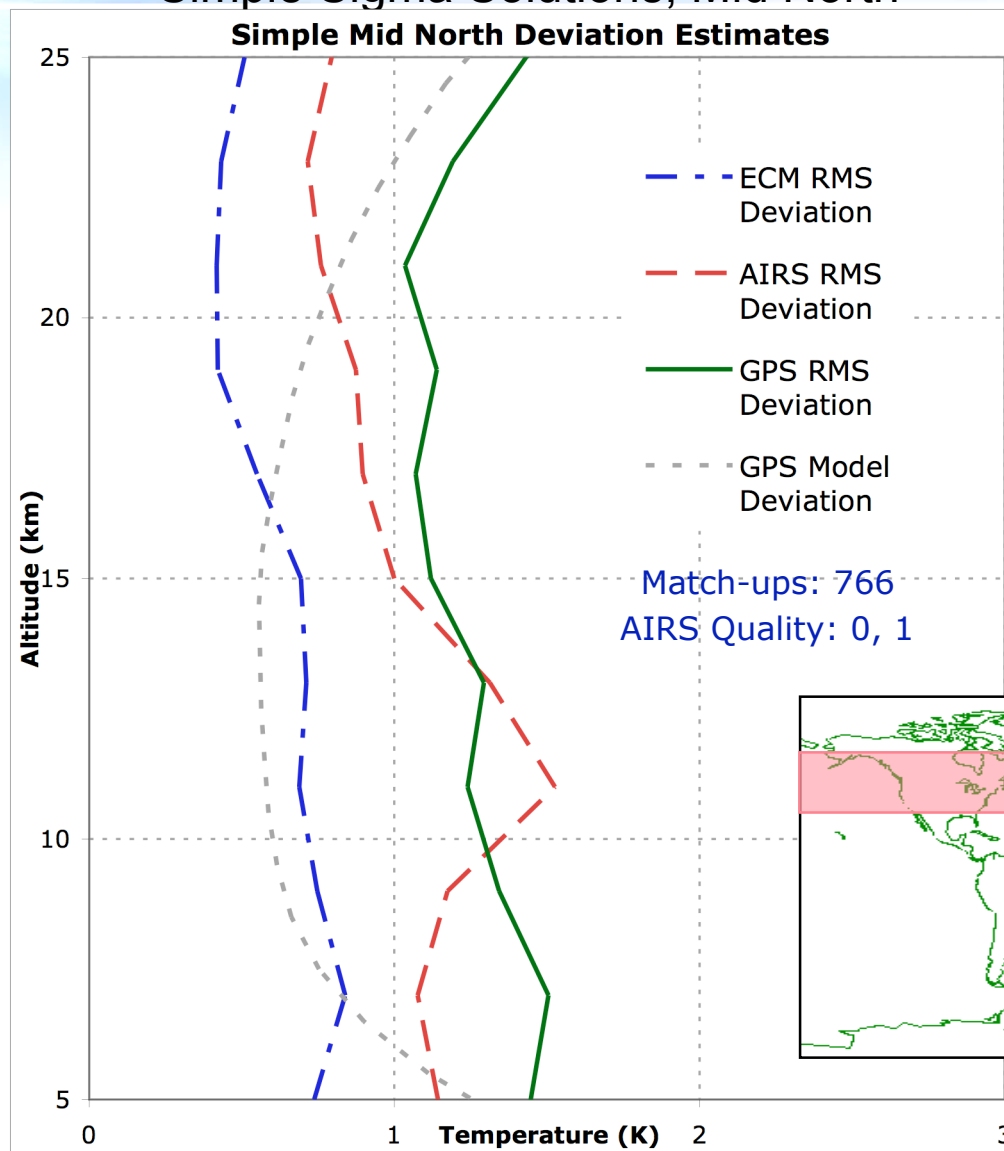


Working Hypothesis

1. AIRS “first guess” temperatures, *trained on ECMWF model*, closely reproduce location-dependent ECMWF bias characteristics.
2. Where temperature gradients are small, AIRS retrieval information is weak and departures from the first guess are small.
3. This leads to significant correlation in location-dependent biases.
4. Where temperature gradients are steep (near the tropopause), AIRS retrievals are allowed to depart more from the a priori, reducing the AIRS-ECMWF correlation.

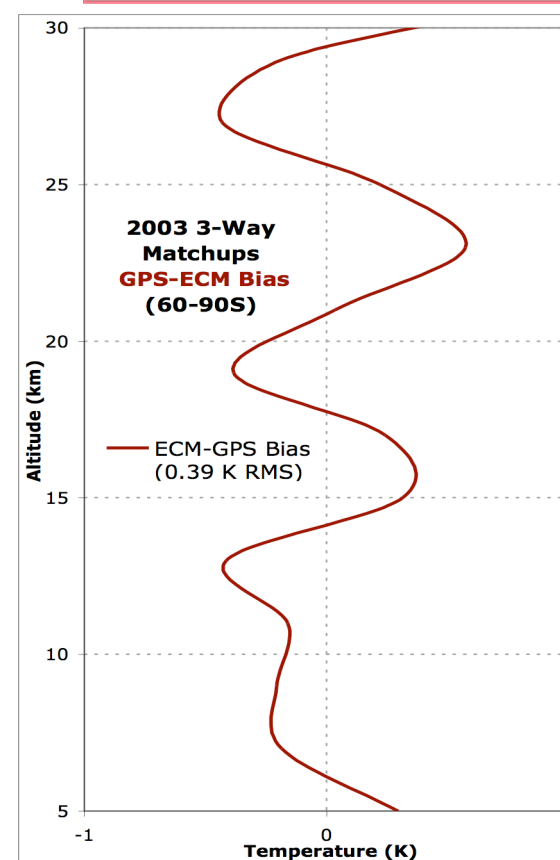
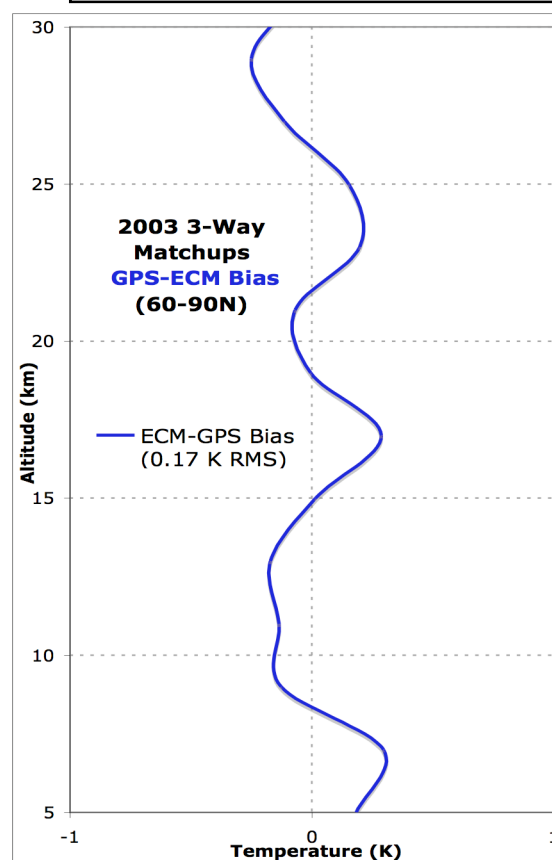
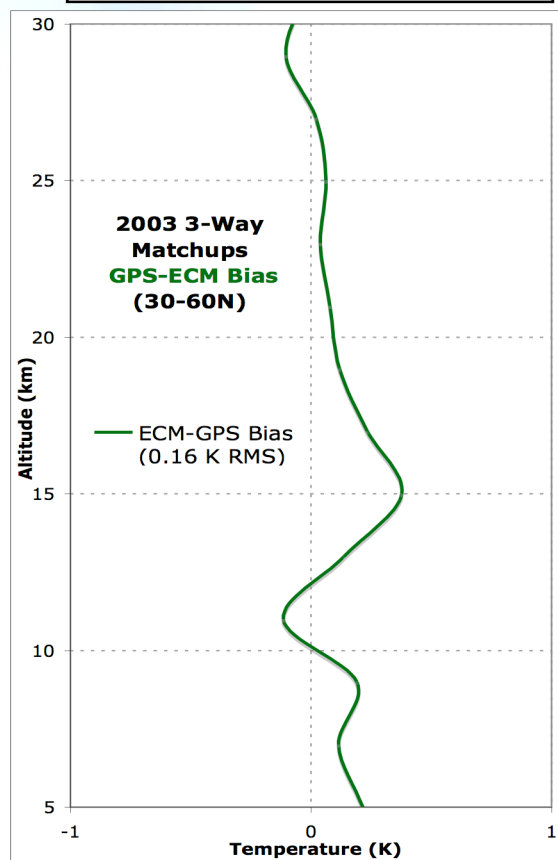
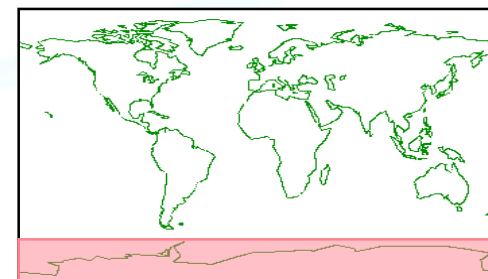
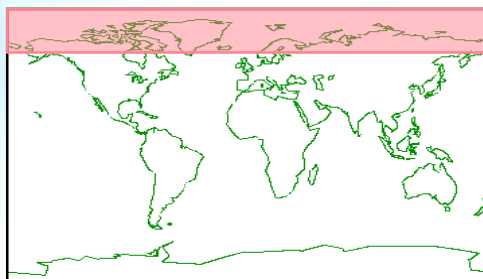
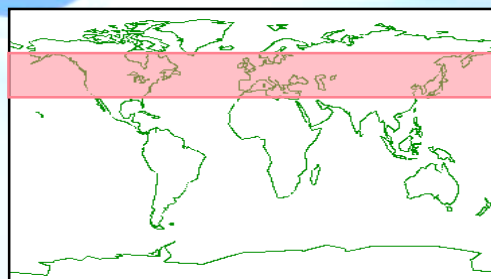


Simple Sigma Solutions, Mid North



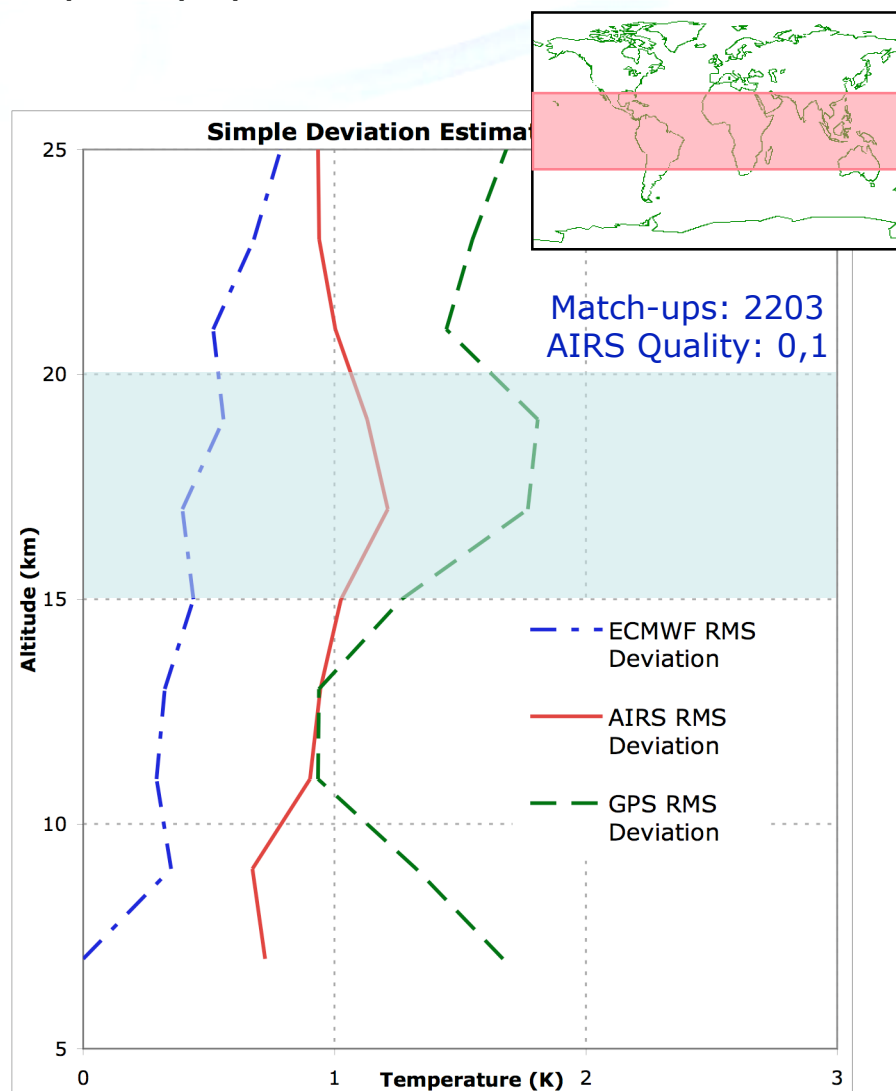
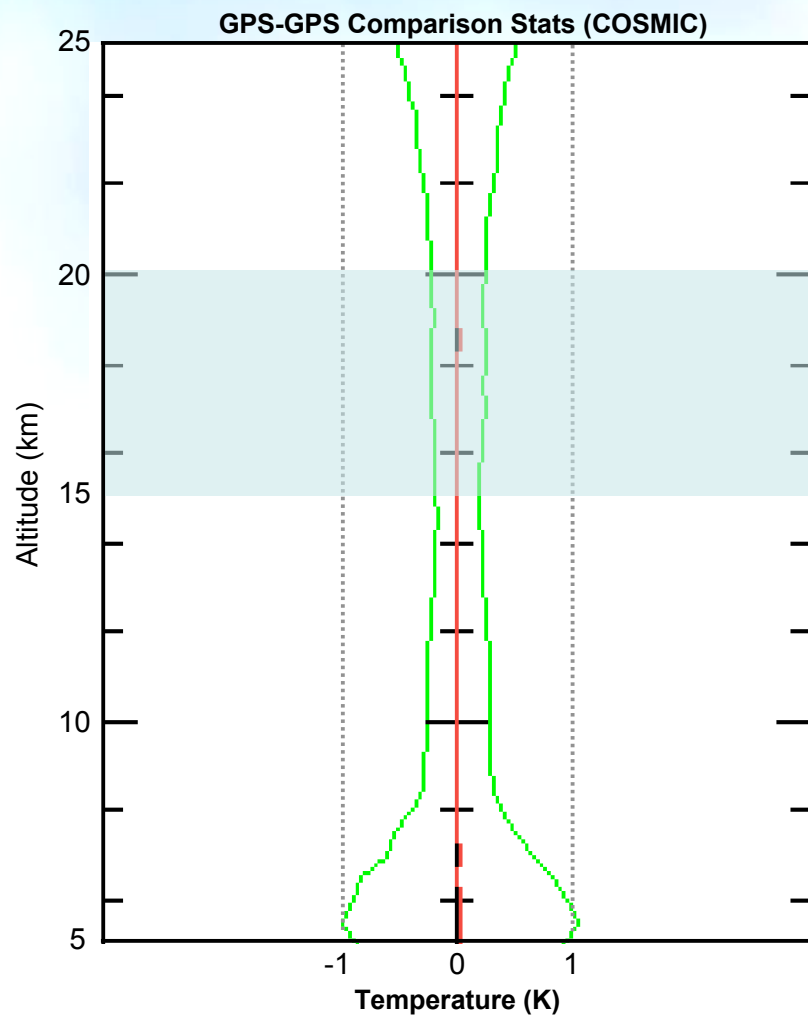


ECMWF-GPS Means, 3-Way Matchups, 2003





Smoothing of Sharp Tropopause





Typical 3-Way Matchup

